

# Flexibility in symplectic and contact geometry

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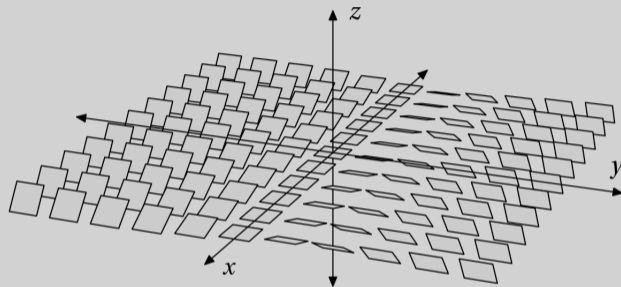
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- $\xi$  on  $Y$  determines and is determined by the structure  $\omega$  on  $X$ , at infinity.

# Example contact structure

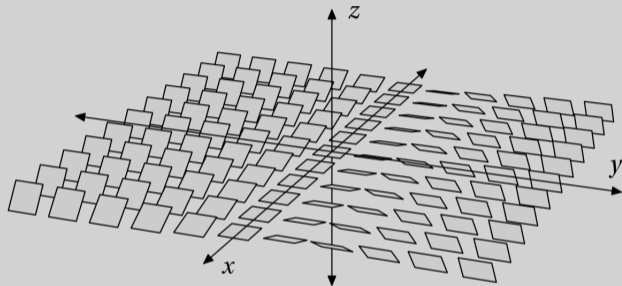
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Every contact manifold can be built by gluing copies of this model together via contactomorphisms.

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For a simple example, a *formal immersion*  $M \rightarrow N$  consists of a bundle monomorphism  $TM \rightarrow TN$ .



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Symplectic and contact geometry one place where this distinction is especially interesting: often the geometry gets very close to the topology!

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Theorem (Casals–Pancholi–Presas 2015, indep. Etnyre)

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Triangulate  $Y$ . Building a contact structure on the codimension 1 skeleton is easy. Thus the problem reduces to extending a contact structure from a neighborhood of  $\partial B^{2n-1}$  to  $B^{2n-1}$ .

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Let  $\varphi_t : (D^{2n-3}, \xi_{\text{std}}) \rightarrow (D^{2n-3}, \xi_{\text{std}})$  be an isotopy through contactomorphisms. Because contact geometry is tied to Hamiltonian dynamics, every contact isotopy comes from an energy function, or Hamiltonian. That is, the Lie algebra of the contactomorphism group  $\text{Cont}(D_{\text{std}}^{2n-3})$  is equal to  $\text{cont}(D_{\text{std}}^{2n-3}) \cong C^\infty(D^{2n-3})$ .

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Following from the elementary theory, by suspending any contact isotopy of  $D_{\text{std}}^{2n-3}$  we obtain a germ of a contact structure near  $S^{2n-2}$ . If the Hamiltonian generating this isotopy is positive everywhere, then the contact structure extends in an obvious way to  $B^{2n-1}$ .



## Proof sketch, continued

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By taking our original triangulation on  $Y$  to be sufficiently fine, we only need to consider contact structures on  $\partial B^{2n-1}$  which are of this suspension type, thus we need to understand how the Lie group  $\text{Cont}(D_{\text{std}}^{2n-3})$  interacts with the positive cone on  $\text{cont}(D_{\text{std}}^{2n-3}) \cong C^\infty(D^{2n-3})$ .

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Besides the adjoint action, we have an additional “monoid structure” coming from contactomorphism  $D_{\text{std}}^{2n-3} \# D_{\text{std}}^{2n-3} \cong D_{\text{std}}^{2n-3}$  (boundary connect sum). We can realize this monoid structure by doing ambient connect sums inside  $Y$ , in this way it becomes an additional tool to construct extensions.

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To complete the proof that any contact structure on  $\partial B^{2n-1}$  extends to the interior, we prove the non-existence of any “causality” on  $\text{Cont}(D_{\text{std}}^{2n-3})$ , which is compatible with the positive cone in  $\text{cont}(D_{\text{std}}^{2n-3})$ , together with the adjoint and connect sum actions.

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Contact structures on compact manifolds have no moduli: any deformation of a contact structure is realized by an ambient isotopy. Thus, **uniqueness is just parametric existence**. That is, if  $\xi_0$  and  $\xi_1$  are contact structures which are homotopic among *formal* contact structures, and if our existence proof is smooth in families, we would obtain a family of contact structures  $\xi_t$  interpolating between  $\xi_0$  and  $\xi_1$ , by which we conclude that  $\xi_0$  is contactomorphic to  $\xi_1$ .

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Nevertheless, this approach is productive for a partial classification, those of [overtwisted contact manifolds](#).

Theorem (Borman–Eliashberg–M., 2015)

*Let  $\eta$  be a formal contact structure on a smooth manifold  $Y$ . Then  $\eta$  is realized by a unique overtwisted contact structure.*

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This generalizes earlier work of [Eliashberg 1989], where the same result was established for 3-manifolds  $Y$ .



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There are many equivalent characterizations of overtwistedness compatible with natural geometric decompositions and submanifolds in contact geometry [Casals–M.–Presas]. Ultimately, the most essential property of overtwistedness is **semi-locality**: there is an overtwisted contact structure on the open ball, and any contact manifold containing an overtwisted open set is itself overtwisted.

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The general structure of  $\Theta$  is poorly understood. For instance, we do not know if there are any units in this monoid, or zero divisors.

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If  $\Lambda \subseteq Y = X \cap \mathcal{S}^{2N-1}$  for  $X \subseteq \mathbb{C}^N$ , and  $L = (-\varepsilon, \varepsilon) \times \Lambda \subseteq X$  is defined by the gradient flow of  $|\cdot|^2|_X$ , then  $L$  is Lagrangian if and only if  $\Lambda$  is Legendrian.

# Yet again: topology vs. geometry

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We can define **formal Lagrangian** and **formal Legendrian** submanifolds. These are smooth embeddings  $L \subseteq X$  or  $\Lambda \subseteq Y$  which are “homotopically framed” like Lagrangians/Legendrians.



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Often the topology disagrees with the geometry: for instance there is a formal Lagrangian  $S^3 \subseteq \mathbb{C}^3$ , but there is no genuine Lagrangian in  $\mathbb{C}^3$  diffeomorphic to  $S^3$  [Gromov 1985].

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Theorem (M.)

*Let  $(Y, \xi)$  be a contact manifold of dimension at least 5. Then every formal Legendrian is isotopic to a unique loose Legendrian.*

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Similar to overtwistedness for contact structures, the most important property defining loose Legendrians is that it is semi-local.

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Theorem (Eliashberg–M. 2013, Ekholm–Eliashberg–M.–Smith 2013)

*Let  $L$  be any closed 3–manifold, then there is a Lagrangian embedding  $L \# S^2 \times S^1 \subseteq \mathbb{C}^3$ .*

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These Lagrangians are additionally interesting because they are “exotic” from the perspective of Lagrangian Floer theory: there are no pseudo-holomorphic curves passing through a generic point.

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Theorem (Ekholm–Eliashberg–M.–Smith 2013, Ekholm–Smith 2016, Eliashberg–M. 2013)

*Let  $L \looparrowright \mathbb{C}^{2n}$  be an exact Lagrangian immersion, with only a single transverse double point. Then  $\chi(L) = \pm 2$ . If  $\chi(L) = +2$ , then  $L$  is diffeomorphic to  $S^{2n}$ . If  $\chi(L) = -2$ , then  $L$  can be diffeomorphic to any smooth manifold with the property that  $TL \otimes \mathbb{C}$  is trivial.*

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Combining Morse theory with symplectic geometry lets us understand symplectic manifolds via Legendrians, as “attaching spheres”. Combining this with loose Legendrians gives new information about symplectic manifolds.

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*The Russell cubic threefold  $X = \{x + x^2y + w^3 + z^2 = 0\} \subseteq \mathbb{C}^4$  is symplectomorphic to  $\mathbb{C}^3$ .*



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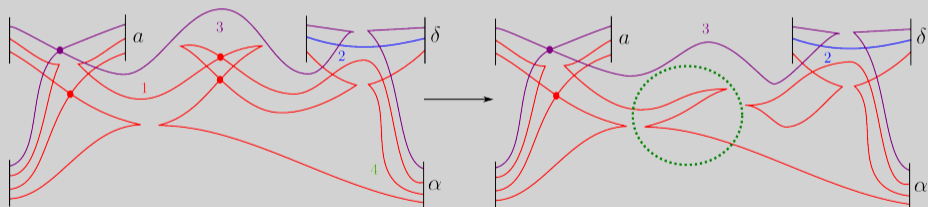
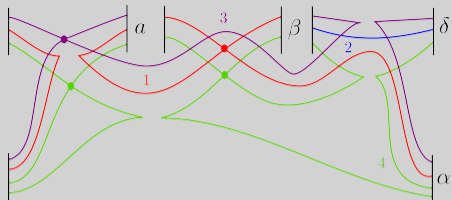
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Trivializing a Koras–Russell cubic. (see [Casals–M.]